

Smooth multi-period forecasting with application to prediction of COVID-19 cases

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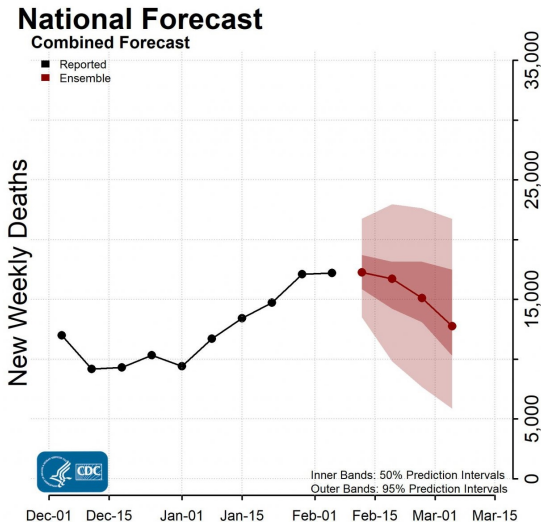
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Goal: predict multiple ahead values of a signal.

Multi-period forecaster (MPF)

Notations:

- location i
- time stamp t
- response signal $Y_i(t)$
- feature signals $X_i(t) = (X_{i1}(t), \dots, X_{ip}(t))$
- ahead values $A = \{a_1, \dots, a_q\} \in \mathbb{R}_{\geq 0}^q$
- lags for k -th feature signal $L_k = \{\ell_{k1}, \dots, \ell_{km_k}\} \in \mathbb{R}_{> 0}^{m_k}$
- set of all $L = \{L_1, \dots, L_p\}$

Multi-period forecaster (MPF)

Goal: for location i and timestamp t predict the response variable for all the ahead values, i.e.

$$Y_i(t + A) = (Y_i(t + a_1), \dots, Y_i(t + a_q)) \in \mathbb{R}^q,$$

using all the lagged features, i.e.

$$X_i(t - L) = (X_{i1}(t - L_1), \dots, X_{ip}(t - L_p)) \in \mathbb{R}^m.$$

Here, $m = \sum_{k=1}^p m_k$ and, by analogy with the response,

$$X_{ik}(t - L_k) = (X_{ik}(t - \ell_{k1}), \dots, X_{ik}(t - \ell_{km_k})) \in \mathbb{R}^{m_k}.$$

Baseline model: for each location i , timestamp t and ahead $a \in A$

$$Y_i(t+a) = \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) b_{k\ell}(a) + \epsilon_i(t+a).$$

We collect the data for locations $i = 1, \dots, n$ and timestamps $T = \{t_1, \dots, t_N\}$ and form the **baseline MPF loss**

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A} \left(Y_i(t+a) - \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) b_{k\ell}(a) \right)^2.$$

Comment: the loss can be optimized separately for each a .

$$\underset{B \in \mathbb{R}^{m \times q}}{\text{minimize}} \|Y - XB^T\|_F^2 \implies \hat{B}^T = (X^T X)^{-1} X^T Y$$

Assume that $b_{k\ell}(a)$ is a *smooth function* of ahead values \implies

$$b_{k\ell}(a) = \sum_{j=1}^d \theta_{jk\ell} h_j(a)$$

for some basis $h_1(a), \dots, h_d(a)$ and coefficients $\theta_{jk\ell} \in \mathbb{R}$

Smooth MPF loss

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A} \left(Y_i(t+a) - \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) \sum_{j=1}^d \theta_{jk\ell} h_j(a) \right)^2$$

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Comment: unlike the baseline MPF, the loss cannot be optimized separately for each a .

$$\underset{\Theta \in \mathbb{R}^{d \times m}}{\text{minimize}} \|Y - X\Theta^T H^T\|_F^2 \implies \hat{\Theta}^T = (X^T X)^{-1} X^T Y H$$

Weighted smooth MPF

Assume that for each location and timestamp the set of aheads vary
 \implies we replace A by $A_i(t) \subseteq A$

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A_i(t)} \left(Y_i(t+a) - \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) \sum_{j=1}^d \theta_{jk\ell} h_j(a) \right)^2$$

Example: some counties did not submit the data.

Weighted smooth MPF

Assume that for each location and timestamp the set of aheads vary
 \implies we replace A by $A_i(t) \subseteq A$

Weighted smooth MPF loss

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A} W_i(t+a) \left(Y_i(t+a) - \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) \sum_{j=1}^d \theta_{jk\ell} h_j(a) \right)^2$$

where $W_i(t+a) = \begin{cases} 1 & \text{if } a \in A_i(t), \\ 0 & \text{otherwise.} \end{cases}$

Weighted smooth MPF

Assume that for each location and timestamp the set of aheads vary
 \implies we replace A by $A_i(t) \subseteq A$

Weighted smooth MPF loss

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A} W_i(t+a) \left(Y_i(t+a) - \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) \sum_{j=1}^d \theta_{j k \ell} h_j(a) \right)^2$$

Comment: because of the weights pre-multiplication trick does not work anymore.

Weighted smooth MPF

$$\underset{\Theta \in \mathbb{R}^{d \times m}}{\text{minimize}} \|W \circ (Y - X\Theta^T H^T)\|_F^2 \implies \underset{\theta \in \mathbb{R}^{dm}}{\text{minimize}} \|w \circ (y - \tilde{X}\theta)\|_2^2$$

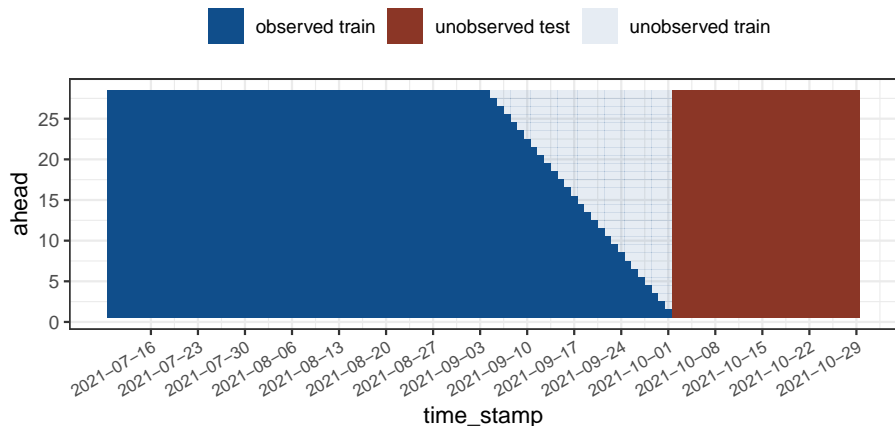
Signals:

- `confirmed_7dav_incidence_prop` – the daily number of new confirmed COVID-19 cases (per 100,000 people);
- `smoothed_cli` – the estimated percentage of people with COVID-like illness;
- `smoothed_hh_cmnty_cli` – the estimated percentage of people reporting illness in their local community.

Model:

- i represents a U.S. county;
- four weeks of aheads $A = \{0, 1, \dots, 27\}$;
- four weeks of lags $L = \{1, 2, \dots, 28\}$;

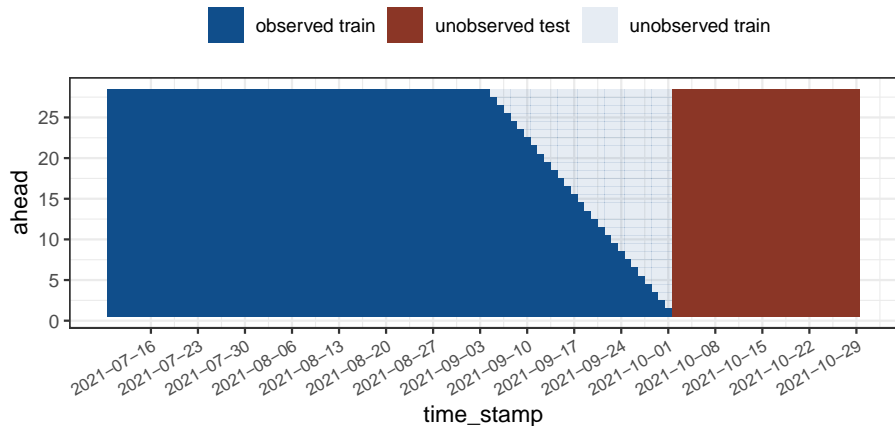
COVIDCast example



Scenario 1: timestamps $T_{train} = \{10\text{-Jul-2021}, \dots, 4\text{-Sep-2021}\}$
 $T_{test} = \{2\text{-Oct-2021}, \dots, 29\text{-Oct-2021}\}$

Methods: baseline MPF and smooth MPF.

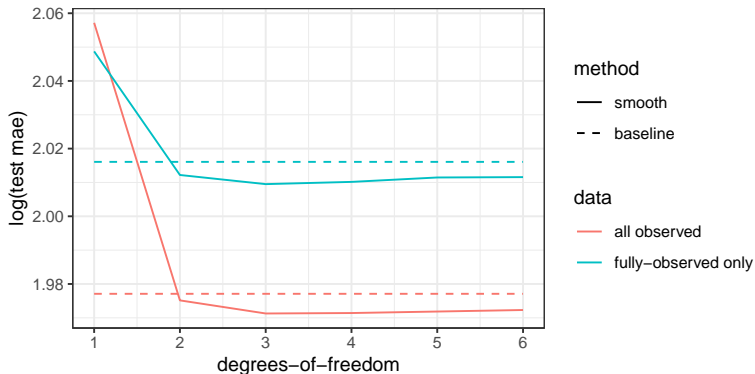
COVIDCast example



Scenario 2: timestamps $T_{train} = \{10\text{-Jul-2021}, \dots, 1\text{-Oct-2021}\}$
 $T_{test} = \{2\text{-Oct-2021}, \dots, 29\text{-Oct-2021}\}$

Methods: weighted baseline MPF and weighted smooth MPF.

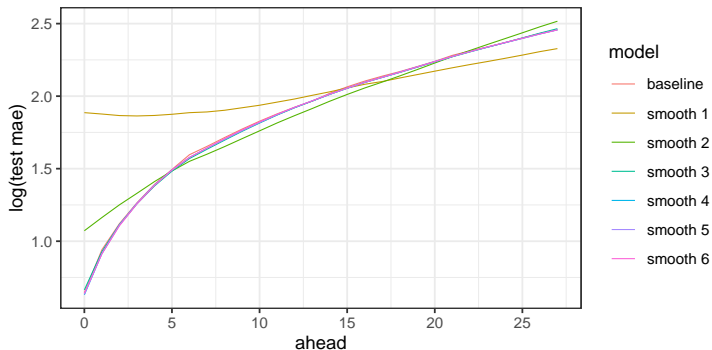
COVIDCast example: point prediction



Interpretation:

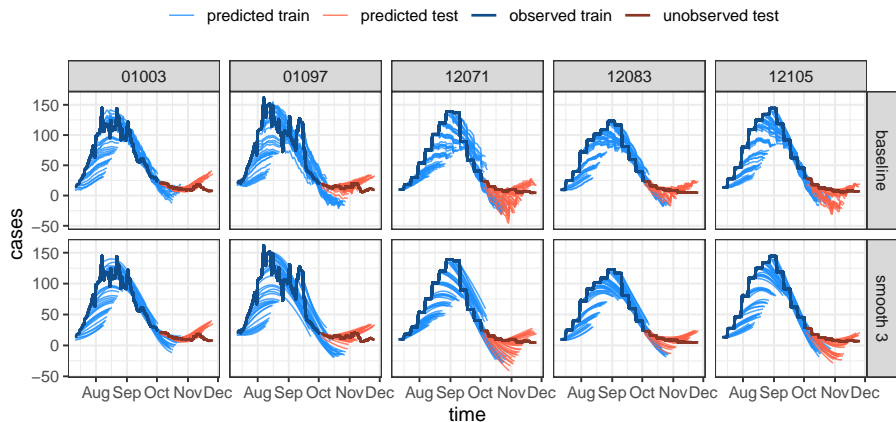
- superior performance of the smooth model;
- weights allow us to include more recent information thereby improving the performance;

COVIDCast example: point prediction



Interpretation: forecasting is more challenging for times which are further in the future.

COVIDCast example: point prediction



Interpretation: the baseline MPF fit demonstrates irregular behavior which is moderated by smoothing.

Quantile multi-period forecaster (QMPF)

For a quantile $\tau \in [0, 1]$ consider **the pinball loss function**

$$\rho_{\tau}(y, \hat{y}) = \begin{cases} \tau(y - \hat{y}) & \text{if } y \geq \hat{y}, \\ (1 - \tau)(\hat{y} - y) & \text{otherwise.} \end{cases}$$

Quantile MPF loss

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A_i(t)} \rho_{\tau} \left(Y_i(t + a), \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t - \ell) b_{k\ell}(a) \right)$$

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Smooth QMPF loss

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A_i(t)} \rho_\tau \left(Y_i(t+a), \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) \sum_{j=1}^d \theta_{jkl} h_j(a) \right)$$

Quantile multi-period forecaster (QMPF)

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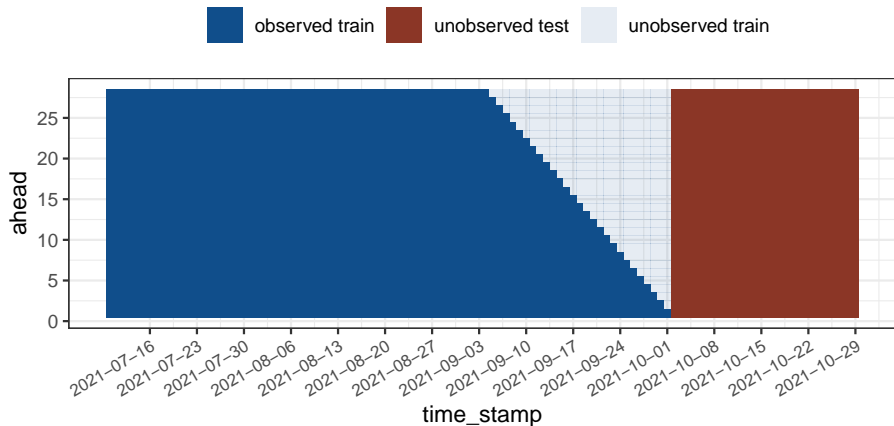
Weighted smooth QMPF loss

$$\sum_{i=1}^n \sum_{t \in T} \sum_{a \in A} W_i(t+a) \cdot \rho_\tau \left(Y_i(t+a), \sum_{k=1}^p \sum_{\ell \in L_k} X_{ik}(t-\ell) \sum_{j=1}^d \theta_{jk\ell} h_j(a) \right)$$

Weighted smooth quantile MPF

$$\underset{\theta \in \mathbb{R}^{dm}}{\text{minimize}} \sum_{i=1}^{Nnq} w_i \cdot \rho_{\tau}(y_i, \tilde{X}_i^{\top} \theta).$$

Calibration

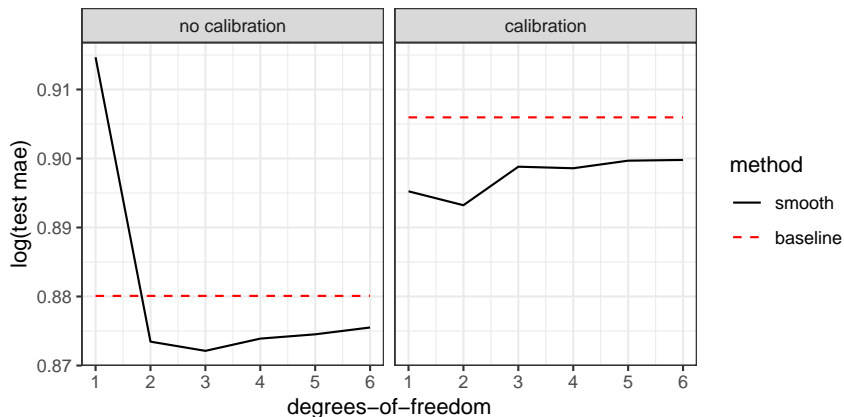


$$T_{\text{train}}^{\text{fit}} = \{10\text{-Jul-2021}, \dots, 3\text{-Sep-2021}\}$$

$$T_{\text{train}}^{\text{cal}} = \{4\text{-Sep-2021}, \dots, 1\text{-Oct-2021}\}$$

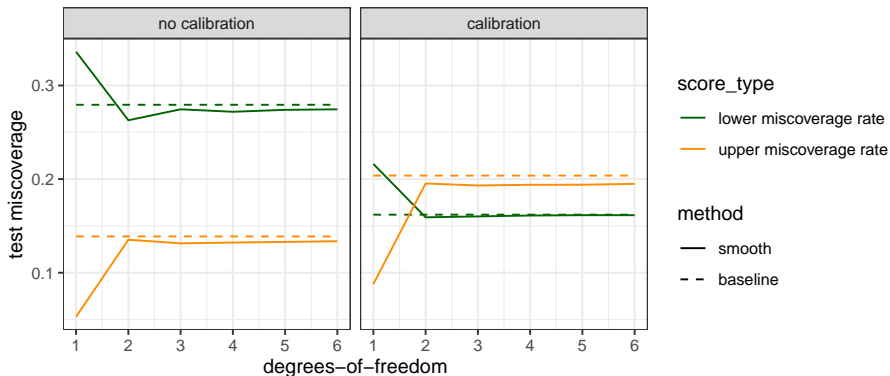
$$T_{\text{test}} = \{2\text{-Oct-2021}, \dots, 29\text{-Oct-2021}\}$$

COVIDCast example: interval prediction



Interpretation: smoothing improves the performance.

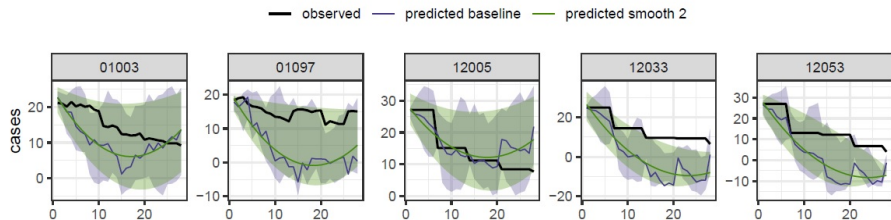
COVIDCast example: interval prediction



Interpretation:

- calibration improves coverage;
- improved performance of the smooth model relative to the baseline.

COVIDCast example: interval prediction



Interpretation: SQMPF results in a smooth trajectory and smooth bounds of prediction interval.

Thank you for your attention!